

PJM Manual 07:

PJM Protection Standards

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Prepared by
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Department

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Table of Contents

Approval.....	6
Current Revision.....	7
Introduction.....	8
About PJM Manuals.....	8
About This Manual.....	8
Using This Manual.....	9
Section 1: Applicability.....	10
Section 2: Protection Philosophy and Reliability.....	11
2.1 Reliability.....	11
2.1.1 Test Switches.....	11
2.1.2 Instrument Transformers.....	11
2.1.3 Communication Channels.....	11
2.1.4 Station Batteries.....	11
2.1.5 Station Service (AC Supply).....	12
Section 3: Generator Protection.....	13
3.1 Generator Stator Fault Protection.....	13
3.1.1 Phase Fault Protection.....	13
3.1.2 Ground Fault Protection.....	13
3.2 Generator Rotor Field Protection.....	13
3.3 Generator Abnormal Operating Conditions.....	14
3.3.1 Loss of Excitation (Field).....	14
3.3.2 Unbalanced Current Protection.....	14
3.3.3 Loss of Synchronism.....	14
3.3.4 Overexcitation.....	14
3.3.5 Reverse Power (Anti-Motoring).....	15
3.3.6 Abnormal Frequencies.....	15
3.3.7 Generator Breaker Failure Protection.....	15
3.3.8 Excitation System Tripping.....	15
3.3.9 Generator Open Breaker Flashover Protection.....	15
3.3.10 Protection During Start-up or Shut-down.....	16
3.3.11 Inadvertent Energization Protection.....	16
3.3.12 Synchronizing Equipment.....	16
3.3.13 Generator Lead Protection.....	16

Section 4: Unit Power Transformer and Lead Protection.....	17
4.1 Transformer Fault Protection.....	17
4.2 Transformer High-Side Lead Protection.....	17
4.3 Overexcitation Protection.....	17
Section 5: Unit Auxiliary Transformer and Lead Protection.....	18
5.1 Transformer and Low-Side Lead Protection.....	18
5.2 Transformer High-Side Lead Protection.....	18
Section 6: Start-up Station Service Transformer and Lead Protection.....	19
6.1 Transformer and Low-Side Lead Protection.....	19
6.2 Transformer High-Side Lead Protection.....	19
Section 7: Line Protection.....	20
7.1 General Requirements.....	20
7.1.1 Current Sources.....	20
7.1.2 Voltage Sources.....	20
7.2 Primary Protection.....	20
7.3 Back-up Protection.....	20
7.4 Restricted Ground Fault Protection.....	21
7.5 Close-in Multi-Phase Fault Protection (Switch-Onto-Fault Protection).....	21
7.6 Out-of-Step Protection.....	21
7.7 Single-Phase Tripping.....	22
Section 8: Substation Transformer Protection.....	23
8.1 Transformer Protection.....	23
8.1.1 Bulk Power Transformers.....	23
8.1.2 All other substation transformers.....	23
8.1.3 Sudden Pressure Relay Applications.....	23
8.1.4 Current Differential Zone Considerations.....	23
8.2 Isolation of a Faulted Transformer Tapped to a Line.....	24
8.2.1 Transformer HV Isolation Device Requirements.....	24
8.2.2 Protection Scheme Requirements.....	24
8.2.3 Protection Scheme Recommendations.....	25
8.3 Transformer Leads Protection.....	26
Section 9: Bus Protection.....	27
Section 10: Shunt Reactor Protection.....	28

Section 11: Shunt Capacitor Protection	29
11.1 Primary Leads Protection.....	29
11.2 Unbalance Detection Scheme.....	29
11.3 Capacitor Bank Fusing.....	29
Section 12: Breaker Failure Protection	30
12.1 Local breaker failure protection requirements.....	30
12.2 Direct transfer trip requirements (See also Appendix B).....	30
12.3 Breaker failure scheme design requirements.....	30
12.4 Pole Disagreement Tripping.....	31
12.5 Live tank circuit breakers.....	31
12.6 Current transformer support columns.....	31
Section 13: Phase Angle Regulator Protection	32
13.1 Detailed Protection Requirements.....	32
Section 14: Transmission Line Reclosing	34
14.1 Reclosing Requirements.....	34
14.2 High-Speed Reclosing Requirements.....	34
Section 15: Supervision and Alarming of Relaying and Control Circuits	36
15.1 Design Standards.....	36
15.2 Relaying Communication Channel Monitoring and Testing.....	36
Section 16: Underfrequency Load Shedding	37
Section 17: Special Protection Schemes/Remedial Action Schemes	38
17.1 Introduction.....	38
17.2 Installation Requirements.....	38
Appendix A: Use of Dual Trip Coils	39
Appendix B: Direct Transfer Trip Requirements	40
Appendix C: Dual Pilot Channels for Protective Relaying	41

Appendix D: Small Generator Protection Requirements.....45

Appendix E: Acceptable Three Terminal Line Applications.....46

Revision History..... 48

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Section 7: Line Protection

This section outlines the requirements for the protection of lines at system voltages above 200 kV and for Critical BES lines built after January 1, 2012 in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE C37.113 Guide for Protective Relay Applications to Transmission Lines

7.1 General Requirements

Two independent protection schemes are required for all lines covered by these requirements. For the purposes of this document, these schemes will be referred to as primary and backup. Both schemes must be capable of detecting all types of faults including maximum expected arc resistance that may occur at any location on the protected line.

Both primary and backup protection schemes must employ independent current and voltage sources and independently protected DC control circuits. Details on the requirements for the current and voltage sources are provided below.

7.1.1 Current Sources

Independent current transformers (CTs) are required for the primary and backup line protection schemes. For dead tank breakers, both primary and backup relays shall be connected such that breaker faults will be detected by the primary and backup relays of both protection zones adjacent to the breaker. Overlapping zones of protection are required in all cases.

7.1.2 Voltage Sources

Independent voltage sources are required for the primary and backup line protection schemes unless one of the schemes operates based on current only such as a current differential scheme. The following design options are acceptable:

- Independent voltage transformers (VTs)
- Independent secondary windings of the same VT

7.2 Primary Protection

The primary line protection scheme must provide high-speed simultaneous tripping of all line terminals. The scheme must have sufficient speed so that it will provide the required fault clearing times for system stability as defined in the NERC TPL-001 Transmission Planning Standard. To meet the speed and coverage requirements as defined above, a high speed communication channel is required for this scheme.

7.3 Back-up Protection

The back-up line protection scheme shall be independent of the primary line protection scheme and must utilize independent current and voltage sources and independently protected DC control circuits. The following requirements apply for the back-up protection:

- Relays from the same manufacturer are acceptable for both the primary and back-up systems. The use of different models is recommended but not required.

- Back-up protection must have sufficient speed to provide the clearing times necessary to maintain system stability as defined in the NERC TPL Transmission Planning Standards.
- The back-up protection may require the inclusion of a communications-assisted tripping system in order to meet clearing time requirements. In such cases, the communication path must be independent of the communication path for the primary relays. Refer to Appendix C for further details on requirements for the communications channels. When redundant communications-assisted protection is required, alarms must be provided sufficient to detect a failure which disables both primary and back-up communications-assisted tripping.
- One protection scheme must always include a non-communications-assisted tripping scheme for phase and ground faults, regardless of whether a backup communications-assisted tripping system is employed.
 - Non-communications-assisted instantaneous impedance based protection (traditionally referred to as Zone 1) or instantaneous directional overcurrent protection is required for all line terminals unless the line impedance is insufficient for both reliable and secure operation. This protection scheme shall be set to operate without additional time delay (other than as required to override transient overreach behavior) and to be insensitive to faults external to the protected line.
 - Non-communications-assisted time delayed impedance based protection (traditionally referred to as Zone 2) or time delayed directional overcurrent protection is required for all line terminals. This protection scheme shall be set with sufficient time delay to coordinate with adjacent circuit protection including breaker failure protection. For two-terminal-line applications, sufficient sensitivity is required to provide complete line coverage of the protected line. For three-terminal-line applications, see Appendix E

7.4 Restricted Ground Fault Protection

A scheme must be provided to detect ground faults with high fault resistance. The relay(s) selected for this application must be set at 600 primary amperes or less, provided that this setting is greater than the maximum line zero-sequence load unbalance. These relays may serve as the overreaching non-communications-assisted ground tripping function.

7.5 Close-in Multi-Phase Fault Protection (Switch-Onto-Fault Protection)

Protection must be provided to clear zero-voltage faults present when a line is energized with the relay potential source provided by line-side voltage transformers. A scheme designed to specifically provide this protection must be provided if this protection is not inherently provided by the primary and/or back-up line protection schemes. Scheme redundancy is not required.

7.6 Out-of-Step Protection

Out-of-step protection is typically not utilized within the PJM system. The application of out-of-step relays in any transmission application must be reviewed and approved by the PJM Planning Department, with input from the PJM Relay Subcommittee as necessary.

7.7 Single-Phase Tripping

Single-phase tripping is typically not utilized within the PJM system. The application of single-phase tripping must be reviewed and approved by the PJM Planning Department, with input from the PJM Relay Subcommittee as necessary.

Section 8: Substation Transformer Protection

This section outlines the requirements for the protection of substation transformers with high-side voltages of 200kV and above or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE C37.91 Guide for Protective Relay Applications to Power Transformers
- ANSI/IEEE C37.110 Guide for the Application of Current Transformers Used for Protective Relaying Purposes

8.1 Transformer Protection

8.1.1 Bulk Power Transformers

Bulk Power Transformers are transformers with low-side voltages greater than or equal to 100 kV and networked on the low side

Two independent high-speed protection schemes are required. Acceptable combinations of schemes for satisfying the redundancy requirement are the following:

- Two independent current differential schemes
- One current differential scheme and one sudden pressure relay scheme

Independently protected DC control circuits are required.

8.1.2 All other substation transformers

Two independent protection schemes, at least one of which must be high-speed, are required. Acceptable combinations of schemes for satisfying the redundancy requirement are the following:

- Two independent current-based schemes, one of which must be differential
- One current-based scheme and one sudden pressure relay scheme

Independently protected DC control circuits are required.

8.1.3 Sudden Pressure Relay Applications

When a sudden pressure relay scheme is used as one of the two independent protection schemes and the transformer has a tap changer in a compartment separate from the main tank, the sudden pressure relay scheme must use sudden pressure relays in both the main tank and the tap changer compartment.

8.1.4 Current Differential Zone Considerations

If the transformer current differential zone is extended to include the bus between breakers on the high or low sides of the transformer, the current circuit from each breaker must be connected to separate restraint windings in the differential relay, with the following exception. Two or more current circuits may be paralleled into one restraint winding only if current can flow in no more than one of the paralleled circuits for all faults external to the differential protective zone (i.e., radial feeder breakers with no source of fault current).

8.2 Isolation of a Faulted Transformer Tapped to a Line

This section addresses the requirements for isolating a fault on a transformer tapped on a line. Bulk power lines operated at greater than 300 kV shall not be tapped. Lines operated at less than 300 kV lines may be tapped with the concurrence of the transmission line owner(s).

8.2.1 Transformer HV Isolation Device Requirements

This section is concerned with the isolation of power transformers tapped a line.

All transformers tagged to a line require a device (e.g. circuit breaker, circuit switcher, disconnect switch, etc.) which will automatically isolate the transformer from the line following transformer fault clearing.

Transformers with low-side voltage ratings less than 60 kV are at increased risk of having animal contacts. Therefore, a fault interrupting device capable of interrupting low-side faults is required for transformers with low-side voltage ratings less than 60 kV in order to prevent tripping the tapped line.

Since Bulk Power Transformers have low-side voltage ratings above 100 kV, they are considered less prone to animal contact and therefore are not required to have fault interrupting devices.

Fault interrupting devices do not have to be rated to interrupt all faults within the transformer zone of protection (i.e. circuit switchers may not be capable of interrupting source side faults). An alternate means of tripping for faults exceeding the capability of the device will be required. Protection and coordination requirements for transformer primary faults shall be determined by, or in discussions with the transmission line owner(s). Examples of alternate means of tripping for primary transformer faults are direct transfer trip or remote line relay operation.

When a fault interrupting device is not required and is not installed, a motor operated disconnect switch will be required on the tapped line side of the transformer. The switch will isolate the transformer after the fault has been cleared to allow line restoration. The switch will be opened by the transformer protection schemes in coordination with the clearing of the tapped line.

In cases where an increased exposure to line tripping is a reliability concern, the use of a high side-interrupting device will be required.

8.2.2 Protection Scheme Requirements

A fault interrupting device requires a device failure scheme when the transformer associated with the failed device serves anything other than a radial distribution load or independent from it. The requirement to install a disconnect switch and any requirements for the operation of the switch shall be determined by, or in discussions with the when the transmission line owner(s) requires it.

- When a device failure scheme is required for a fault interrupting device that is fully rated for all faults on the transformer, the following are acceptable schemes for isolating the faulted transformer for the contingency of a stuck interrupting device:
 - o Direct transfer trip scheme
 - o Second interrupting device
 - o Ground switch and motor operated disconnect switch combination.

- When the interrupting device is not fully rated to interrupt all faults in the transformer zone of protection, such as a disconnect switch or a circuit switcher that is not rated to interrupt high side faults on the transformer, the following are acceptable schemes for providing primary and backup fault clearing of the transformer:
 - o Two independent direct transfer trip schemes - Once the remote line terminals have opened, the faulted transformer shall be automatically isolated from the line and automatic reclosing of the line shall be permitted.
 - o Combination of a direct transfer trip scheme and a ground switch - Where carrier direct transfer trip is used, the ground switch and direct transfer trip shall not be connected to the same phase. Once the remote line terminals have opened, the faulted transformer shall be automatically isolated from the line and automatic reclosing of the line shall be permitted.
 - o Remote primary and backup line relays capable of tripping for all faults not cleared by the transformer protection schemes - Once the remote line terminals have opened, the faulted transformer shall be automatically isolated from the line and automatic reclosing of the line shall be permitted.

8.2.3 Protection Scheme Recommendations

Certain situations may require the transformer protection to initiate tripping of the transmission line terminals. For line restoration or other purposes, the tripping logic frequently utilizes auxiliary switch contacts of the primary disconnect switch. The following application recommendations apply. (Elevation of the recommendations to requirements shall be determined by, or in discussions with the transmission line owner(s).

- Auxiliary contacts associated with the disconnect switch operating mechanism (e.g., a motor-operator) should not be used if the mechanism can be de-coupled from the switch. Otherwise, the switch may indicate open when it is in fact closed, likely defeating desired protection functions. A separate auxiliary switch assembly attached to the operating shaft of the switch itself should be used.
- Due to dependability concerns with auxiliary switches, it is recommended that the transformer primary disconnect switch auxiliary contacts not be used in such a manner that if the auxiliary switch (i.e., 89a) contact were to falsely indicate that the disconnect switch is open, the required tripping of local breakers or the direct transfer tripping of remote breakers would be defeated. The use of auxiliary switches in the protection scheme should be limited to local trip seal-in, direct transfer trip termination, etc. For example, assume that a fault occurs within the transformer with a magnitude which exceeds the capability of the interrupter, but cannot easily be detected by the line relays at the terminals. Trip (local and/or remote) logic of the form $T = 94 + T * 89a$ is permissible. Trip logic of the form $T = 94 * 89a$ is not recommended. Alternatively, trip logic of the form $T = 94 * (89a + 50)$ may be acceptable, where "50" is a current detector set as low as practical and connected to monitor current through the switch.
- Using the above example, if the transformer is connected in such a manner that it can be switched between two bulk-power lines, there may be no alternative than to use auxiliary switch contacts to determine which line to trip. In this case, any redundancy requirements will extend to the auxiliary switches, which should be electrically and mechanically independent.

8.3 Transformer Leads Protection

The transformer high and low side leads must be protected by two independent schemes, both of which must be high-speed unless the leads are included in a line protection zone. The schemes must utilize independent current and/or voltage sources and independently protected DC control circuits. Where the voltage rating of the low-side leads is less than 100 kV, redundancy in the low side lead protection is not required.

Blind spots in a lead protection scheme can result during an operating condition, such as an open disconnect switch, where a portion of the transformer leads may be unprotected. If a blind spot in the lead protection can result from any operating condition, independent protection systems for the blind spot must be provided for the Bulk Power Transformers.

Section 9: Bus Protection

This section outlines the requirements for the protection of substation buses rated 200 kV and above or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE C37.234 Guide for Protective Relay Applications to Power System Buses
- ANSI/IEEE C37.110 Guide for the Application of Current Transformers Used for Protective Relaying Purposes

Two independent high-speed protection schemes are required for protecting the bus. They must utilize independent current and/or voltage sources and independently protected DC control circuits.

Section 10: Shunt Reactor Protection

This section outlines the minimum requirements for the protection of shunt reactors rated 200 kV and above or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE C37.109 Guide for the Protection of Shunt Reactors
- ANSI/IEEE C37.110 Guide for the Application of Current Transformers Used for Protective Relaying Purposes

In general, the requirements for the protection of shunt reactors are functionally equivalent to the requirements for the protection of substation transformers. Some requirements do not apply to reactors, for example those relating to multiple windings.

The specific hardware used for reactor protection will generally be different from that used for transformer protection; however, as noted above, the functional requirements are equivalent and are summarized as follows:

- The reactor must be protected by two independent high-speed schemes. The two schemes must utilize independently protected DC control circuits.
- The reactor leads must be protected by two independent schemes, both of which must be high-speed unless the leads are included in a line protection zone. The two schemes must utilize independent current and/or potential sources and independently protected DC control circuits.
- For additional detail and for other requirements (e.g., the use of auxiliary contacts in the protection scheme), see Section 8 on Substation Transformer Protection.

Section 11: Shunt Capacitor Protection

This section outlines the minimum requirements for the protection of shunt capacitors rated 200 kV and above or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE C37.99 Guide for the Protection of Shunt Capacitor Banks
- ANSI/IEEE C37.110 Guide for the Application of Current Transformers Used for Protective Relaying Purposes
- IEEE 1036-Guide for Application of Shunt Power Capacitors

The following schemes must be provided to protect each capacitor bank:

11.1 Primary Leads Protection

The capacitor bank leads must be protected by two independent schemes, both of which must be high-speed unless the leads are included in a line protection zone. The two schemes must utilize independent current and/or potential sources and independently protected DC control circuits.

11.2 Unbalance Detection Scheme

Primary and back-up capacitor bank unbalance detection schemes must be installed. These schemes should be set to trip the capacitor bank for unbalances resulting in greater than 110% of rated voltage across the individual capacitor cans. For externally-fused capacitor banks, the bank must be designed such that a single can failure does not result in greater than 110% of rated voltage across the remaining cans. Independently protected DC control schemes must be used for each of the schemes. Where potential sensing is used in both the primary and back-up schemes, independent voltage sources are required, with the exception of voltage differential schemes which will result in a trip of the capacitor bank upon the loss of the voltage source to the scheme.

11.3 Capacitor Bank Fusing

For externally fused capacitor banks, the fuse size should be chosen to protect the capacitor can from catastrophic can rupture in the event of an internal can fault. In the case of fuseless banks, the protection scheme operating characteristics and bank design must be selected to protect against catastrophic can ruptures.

Section 12: Breaker Failure Protection

This section outlines the minimum requirements for breaker failure protection for fault interrupting devices (including circuit switchers, where applicable) at system voltages above 200 kV or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE Std C37.119 - IEEE Guide for Breaker Failure Protection of Power Circuit Breakers

12.1 Local breaker failure protection requirements

A dedicated² breaker failure scheme shall be used for each fault-interrupting device and shall initiate tripping of all local sources of fault current.

The breaker failure output tripping relay shall block both manual and automatic closing of all local breakers required to trip until the failed breaker has been electrically isolated.

12.2 Direct transfer trip requirements (See also Appendix B)

Local breaker failure protection shall initiate direct transfer tripping of associated remote terminals if any of the following conditions exist.

- Speed is required to assure system stability.
- Remote back-up protection is unacceptable because of the number of circuits and area affected.
- The sensitivity of remote relay schemes is inadequate due to connected transformers, connected generators, line-end fault levels, or due to strong infeed from parallel sources.

Tripping shall be maintained at the remote terminal until the failed breaker has been electrically isolated.

Automatic reclosing shall be prevented at the remote terminal until the failed breaker has been electrically isolated.

12.3 Breaker failure scheme design requirements

Failure of a single component shall not disable both the tripping of the breaker and the breaker failure scheme.

For security against possible false breaker failure scheme operation, the minimum acceptable margin between normal fault clearing and a breaker failure trip decision is 24 msec.

² A “dedicated” scheme is defined for purposes of this document as one which utilizes a separate breaker failure timer (or timers) for each breaker as opposed to a scheme which utilizes a breaker failure timer common to all breakers supplied by a bus. A dedicated scheme may utilize elements common to other breakers such as an auxiliary tripping relay which trips all breakers on the affected bus.

Current actuated fault detectors are always required. However, when the primary and backup relays detect conditions for which the current actuated fault detectors lack the required sensitivity, breaker auxiliary switches shall also be used.

Breaker failure scheme designs generally include an optional “re-trip” feature whose purpose is to prevent unnecessary breaker failure operations which could occur for various reasons³. The re-trip feature must be implemented unless it has been established that fault-detector settings, scheme logic, or other considerations negate the advantages of the re-trip feature. The re-trip feature must function to re-trip the protected interrupting device upon initiation of the breaker failure scheme.

12.4 Pole Disagreement Tripping

Pole Disagreement Tripping must be installed on all fault interrupting devices capable of individual pole operation. The pole disagreement scheme must incorporate the following features:

- All poles of the device must be opened if the position of one pole fails to agree with the position of either of the other two.
- An alarm specifically for “pole disagreement” must be initiated by the above scheme.
- The disagreement scheme is to trip only the affected device.

12.5 Live tank circuit breakers

Live tank circuit breakers must be provided with high speed flashover protection to detect and isolate a phase-to-ground flashover of the circuit breaker column if the column would be in a blind spot from local protection schemes for such a flashover.

12.6 Current transformer support columns

Current transformer support columns must be provided with high speed flashover protection to detect and isolate a phase-to-ground flashover of the current transformer support column if the current transformers would be in a blind spot from local protection schemes for such a flashover.

³ Applications of the re-trip feature include (1) activation of a second trip coil in recognition of the possibility that the first trip coil may be defective; (2) the attempt to trip the breaker prior to the expiration of breaker failure timing in the event that breaker failure has been initiated without trip having been initiated. Events of the latter type have occurred due to improper test procedures and due to certain relay failure modes.

Section 13: Phase Angle Regulator Protection

This section outlines the minimum requirements for the protection of phase angle regulating transformers connected at system voltages above 200 kV or as defined in this manual Section 1 - Applicability. The protection of phase angle regulating transformers is a highly specialized subject and the design of the protection scheme should take into consideration such factors as application requirements, transformer manufacturer input, design of surrounding system protection systems, and clearing time requirements

The following standards and publications were used as a reference for developing the requirements specified in this section.

- Protection of Phase Angle Regulating Transformers, an IEEE Power System Relaying Committee Report, October 1999
- IEEE Guide for the Application, Specification, and Testing of Phase-Shifting Transformers, IEEE Standard C57.135

13.1 Detailed Protection Requirements

The detailed protection requirements (especially in regard to the differential protection) are highly specific to the transformer winding connections, for which there are different designs in use. The protection scheme is generally developed through discussions with the transformer manufacturer, protection equipment manufacturers, applicable industry guides and technical papers, and through consultations with the interconnecting utility.

The following requirements pertain to the protection of phase angle regulating transformers of all types:

- Individual pressure actuated devices which operate for a change in gas or oil pressure must be provided for each individual winding and Load Tap Changer (LTC) compartment. The operation of these protective devices must be wired to trip the unit.
- A protection scheme to detect an out-of-step tap changer position.
- Independent current sources and independently protected DC control circuits

The following are the minimum requirements specific to the current-derived protection of the most common type of phase angle regulating transformer⁴ in use within PJM

- A primary current differential scheme which includes the primary series winding and the primary excitation (shunt) winding.
- A secondary current differential scheme which includes the secondary series winding and the secondary excitation (LTC) winding.
- An overcurrent scheme for the neutral connection of the primary excitation (shunt) winding.
- An overcurrent scheme for the neutral connection of the secondary excitation (LTC) winding.

⁴ Wye-grounded exciting winding, delta-connected secondary series winding.

Some Phase Angle Regulators are equipped with an “Advance-Retard Switch” (ARS) that reconfigures the series transformer delta winding to control the direction of power flow. The secondary differential scheme must be designed to allow for a full transition from the Advance state to the Retard state and vice-versa. During the transition, the CT delta connection or the CT compensation settings in the secondary differential relay must be modified accordingly without causing the unit to trip. A microprocessor relay capable of multiple setting groups is strongly suggested for the secondary differential protection.

Section 14: Transmission Line Reclosing

This section outlines the requirements for applying automatic reclosing schemes for fault interrupting devices at system voltages above 200 kV or as defined in this manual Section 1 - Applicability.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- ANSI/IEEE Std C37.104 Guide for Automatic Reclosing of Line Circuit Breakers for AC Transmission and Distribution Lines

14.1 Reclosing Requirements

The following requirements must be met when applying automatic reclosing on transmission lines:

- The impact on generator shaft torque of system connected generators due to line reclosing must be considered. An appropriate time delay must be used to maintain the generator shaft torque within acceptable values.
- Reclosing times and sequences must take into account the capability of the fault interrupting device.
- Reclosing for line faults shall not be used on transmission lines consisting entirely of cable. Where combinations of open wire and cable are used, an evaluation should be made to determine if reclosing should be used for faults in the aerial portion of the circuit and blocked for cable faults.
- Automatic reclosing shall be configured to prevent reclosing on a failed transformer or reactor, or on a failed breaker. For such conditions, see the appropriate section for further discussion.
- Automatic reclosing shall not be used where transient voltage analysis studies indicate that reclosing may produce switching surges exceeding equipment design levels.
- Automatic reclosing following out-of-step conditions must be reviewed and approved by PJM Planning Department, with input from the PJM Relay Subcommittee as necessary.

14.2 High-Speed Reclosing Requirements

For purposes of this document, the following statements in ANSI/IEEE Std C37.104 apply:

High-speed autoreclosing: Refers to the autoreclosing of a circuit breaker after a necessary time delay to permit fault arc deionization with due regard to coordination with all relay protective systems. This type of autoreclosing is generally not supervised by voltage magnitude or phase angle.

The following requirements must be met when applying high-speed automatic reclosing (HSR) on transmission lines:

- The reclose interval must be selected to allow for proper de-ionization of the fault arc. Based on voltage level, the minimum dead time required to de-ionize the fault can be determined from the following equation:

$$T=10.5 + (kV/34.5) \text{ cycles}$$

where kV is the rated line-line voltage.

Note:

The equation above is valid for voltages as high as 230 kV but may be overly-conservative at higher voltages. For example, industry experience indicates that 30 cycle dead time is adequate at 765 kV.

- Most applications of HSR do not require study for stability, unless the HSR is on a line electrically close to a line originating at a generating station. If the results from such stability studies indicate that reclosing following a specific type of fault or system condition would result in an unacceptable situation, adaptive reclosing as defined in IEEE Standard C37.104 may be used.
- High-speed reclosing must only be initiated by a communications assisted relaying scheme.

Section 15: Supervision and Alarming of Relaying and Control Circuits

This section outlines the requirements for supervision and alarming of relaying and control circuits applied to protect equipment at system voltages above 200 kV or as defined in this manual Section 1 - Applicability.

15.1 Design Standards

The following conditions shall be reported remotely from unattended stations. Some functions can be grouped together when reporting the alarm condition to the remote site based on common operator response and the availability of alarm points. Facilities shall be provided to indicate the specific trouble at the local site.

- Battery low voltage condition
- Blown fuse on protective relaying DC control circuit
- Loss of AC relaying potential
- Alarm condition of protective relay pilot channels as described in Section 15.2
- Relay trouble alarms where internal alarm features are provided

15.2 Relaying Communication Channel Monitoring and Testing

All relay communication channels must be monitored to detect any channel problems and initiate an alarm. Channels that cannot be monitored due to the use of a normally off state must be tested automatically at least once a day, preferably at both reduced and full power levels.

Section 16: Underfrequency Load Shedding

This section outlines the requirements for under-frequency load shedding within PJM.

- Under-frequency load-shedding (UFLS) schemes shall be designed and implemented in accordance with PJM requirements as outlined in PRC-006, PJM Manual 13 and PJM Manual 36.
- The specific design of an UFLS scheme is left to the UFLS Owner, but the following general comments apply:
 - o The load-shedding scheme shall be distributed in application as opposed to a centralized design.
 - o Loads tripped by the load-shedding scheme shall require manual restoration (local or remote) unless otherwise authorized by PJM.

Section 17: Special Protection Schemes/Remedial Action Schemes

This section outlines the requirements for Special Protection Schemes (SPSs) and Remedial Action Scheme (RAS) which are occasionally employed in response to an abnormal condition or configuration of the electric system.

17.1 Introduction

A Special Protection System (SPS) or Remedial Action Scheme (RAS) is designed to detect abnormal system conditions (e.g., abnormal system configuration) and to automatically take appropriate corrective action to maintain system stability, acceptable system voltages, and acceptable facility loading.

Whereas “normal” protective relaying systems are typically designed to isolate faulted elements, SPS/RAS’s may take seemingly unrelated actions such as the tripping of local or remote system elements (including generators), generator runback, and load shedding.

Transmission line out-of-step tripping, trip blocking, and reclose blocking are not considered to be SPS/RAS’s, nor are standard generator protection functions such as loss-of-field protection, over-excitation protection, and out-of-step protection.

17.2 Installation Requirements

SPS/RAS’s should not be installed as a substitute for good system design or operating practices. Their implementation is generally limited to temporary conditions involving the outage of critical equipment.

The decision to employ an SPS/RAS should take into account the complexity of the scheme and the consequences of misoperation as well as its benefits. The use of an SPS/RAS, like any protection scheme, entails the risk that it will misoperate. However, the consequences of an SPS/RAS misoperation are often more severe than those of fault protection schemes.

When conditions are such that an SPS/RAS is no longer required, the SPS/RAS shall be retired.

For SPS/RAS’s which are needed only under certain conditions, procedures shall be established to ensure that these schemes are disabled when the conditions requiring their use no longer exist.

For SPS/RAS’s which are not normally armed, there may be two levels of action. The first stage is designed to recognize a predetermined condition (often system configuration) and “arm” a second stage. The second stage takes concrete action (e.g., tripping of system elements) if certain subsequent events occur. When the SPS/RAS is armed, there shall be indication of that fact in a manned facility.

Refer to Regional Reliability Organization documentation for additional regional requirements.

Appendix A: Use of Dual Trip Coils

This section outlines the requirements for the use of dual trip coils in circuit breakers.

Dual trip coils must be applied to meet the dependability requirements mandated by this document to assure that a failed trip coil does not result in the failure of a breaker to operate.

If the design of the operating mechanism is such that the simultaneous energization of both trip coils with voltages of opposite polarity results in a failure of the mechanism to operate, testing shall be performed to verify proper polarity of the trip coil circuits.

Undesirable breaker failure operations are possible if the primary trip path is open and tripping is initiated through slower-operating backup relays. Where this is the case, one of the following measures must be taken:

- Energize both sets of trip coils with both the primary and backup relays or at least with the relaying system which is known to be faster. In such designs, care must be taken to maintain independence of the primary and backup control circuitry.
- Use high-speed relays to cover the entire zone of protection for both the primary and backup protection.
- Apply the breaker failure retrip logic to energize the trip coil associated with the slower relays prior to expiration of the breaker failure timer. If identification of the slower relays is difficult, then the retrip logic shall energize both trip coils.
- Apply “cross-trip” auxiliary relays in the breaker tripping control scheme.

Appendix B: Direct Transfer Trip Requirements

This section outlines the requirements for Direct Transfer Trip (DTT) schemes.

Audio tone transceivers operating over analog multiplexed systems - the design of the equipment and/or the scheme must be immune from the effects of frequency translation (or “drift”) in the carrier. This requires the transmission of two tones, one configured to shift up in frequency and the other to shift down in frequency.

Audio tone transceivers operating over digital multiplexed systems – the design of certain older audio tone receivers make them subject to generating false trip outputs in the presence of the type of noise characteristic of digital systems. The audio tone equipment manufacturer should be consulted in regard to the application of the tone equipment in any environment which may include digital transmission for any portion of the communications path.

Digital transceivers – it is required that the overall DTT scheme include addressing capability between transmitters and receivers connected through a multiplexing system or through direct fiber where a fiber patch panel is employed.

Power Line Carrier- When using Frequency Shift Keying (FSK) over power line carrier, the channel integrity is monitored continuously by the presence of a guard signal. An alarm for loss of guard signal shall be sent to the control center. Fault detecting relays will key the frequency shift from guard to trip.

Appendix C: Dual Pilot Channels for Protective Relaying

This section outlines the requirements for the application of dual pilot channels when required by the standards presented in this document. Dual pilot channels are defined as two separate, independent communications channels which are applied to provide high speed clearing for transmission line faults via both the primary and backup relay schemes. Each scheme must have sufficient speed to provide the clearing times necessary to maintain system stability as defined in the NERC Transmission Planning Standards, TPL-001 and the associated Table 1.

The following standards and publications were used as a reference for developing the requirements specified in this section.

- IEEE 643 – IEEE Guide for Power Line Carrier Applications
- ANSI/IEEE C37.93 – IEEE Guide for Power System Protective Relay Applications of Audio Tones over Voice Grade Channels
- ANSI/IEEE C37.113 – Guide for Protective Relay Applications to Transmission Lines

1. Channel Independence

Communications channels utilized for the dual pilot relaying systems must be designed with the same level of independence as the primary and backup protection and control systems.

The following factors are used to determine the level of independence of communications channels used for dual pilot relaying systems:

- Physical relationship between the communication facilities and paths used for both channels
- Physical relationship between the channel path(s) and related power system facilities
- Probability of a simultaneous failure due to physical proximity
- Performance of the relay system in the event of a path failure
- Time required to repair a failed path
- Capability to repair or maintain one pilot channel while keeping the remaining channel fully functional

Steady-state loss of both channels

- Upon loss of both pilot channels, the associated transmission line must be taken out of service, or if possible, tripping delay time reduced to a level at which stability requirements are met and relay coordination is maintained for normal clearing of faults.

2. Applications

The following sections provide the specific requirements for the different types of communications channels.

2.1 Power Line Carrier

Dual independent paths can be achieved by using two separate carrier systems, connected to separate phases. Each carrier system will consist of a transmitter and receiver, hybrids, coax cable, line tuner, Capacitive-Coupled Voltage Transformer (CCVT) and wave trap for each

coupled phase. Signal attenuation must be reviewed and other system arrangements must be used if signal attenuation will be above acceptable levels.

Directional Comparison Blocking (DCB)

- Phase to Ground Coupling – Single Phase: Unacceptable for a dual pilot protection scheme as defined in the beginning of this appendix, but its benefits merits its mention.
- Phase to Ground Coupling – Two Phases: Acceptable but not recommended
- Phase to Phase Coupling – Outer Phase to Outer Phase: Acceptable
- Phase to Phase Coupling – Center Phase to Outer Phase: Recommended

Directional Comparison Unblocking (DCUB)

- Phase to Ground Coupling – Single Phase: Unacceptable for a dual pilot protection scheme.
- Phase to Ground Coupling – Two Phases: Acceptable but not recommended
- Phase to Phase Coupling – Outer Phase to Outer Phase: Acceptable
- Phase to Phase Coupling – Center Phase to Outer Phase: Recommended

2.2 Microwave Radio Channels

Two completely independent microwave systems can rarely be justified from an economic standpoint. However, modern systems are often configured with a high degree of redundancy. To the extent that susceptibility to a common-mode failure is limited to passive equipment generally considered to have an extremely low probability of failure (e.g., a single communications battery or common microwave tower), a single microwave system is acceptable. No single-contingency failure of an active component shall compromise both pilot schemes.

Complete redundancy in the radio frequency path (i.e., two antennas) and in the electronic RF multiplexing equipment is required. No single path failure is permitted to result in the unavailability of both pilot protection schemes for longer than the switching time from normal to alternate facilities which is normally of the order of milliseconds.

2.3 Leased Telephone Circuits

If dual pilot channels are required, they may not both utilize leased telephone circuits.

2.4 Fiber Optic Systems

Dual pilot protection systems utilizing fiber optic communications channels must be designed to maintain high speed coverage for the transmission line in the event of a single contingency. In evaluating the level of redundancy, both the fiber path routing and protection scheme types must be considered. The following protection fiber optic path examples are presented as with protection scheme scenarios of the analysis which must be performed to determine adequate redundancy:

One fiber optic shield wire:

- Two permissive tripping schemes: Unacceptable for dual pilot protection
- A break in the shield wire would disable both protection systems and could create a fault on the protected line.

- In addition, using two fibers in the shield wire may result in the loss of both channels if the shield is damaged and maintenance outages may be difficult to obtain to repair the fibers in a timely manner.
- Two unblocking schemes: Unacceptable for dual pilot protection
- In the case of a broken shield wire, both channels would be disabled if the fault takes longer than 300 msec to develop.
- In addition using two fibers in the shield wire may result in the loss of both channels when the shield is damaged with uncertain repair time.

Two independent fiber optic shield wires:

- Two permissive tripping schemes: Acceptable for dual pilot protection, but not recommended.
- Although this scheme offers some improvement over one fiber optic shield wire utilization, outside interference such as an aircraft could cause the loss of both shield wires during a fault.
- Two unblocking schemes: Acceptable for dual pilot protection, but not recommended.
- This arrangement is similar to the Two permissive tripping schemes, but with the repair problem of one fiber optic shield wire utilization alleviated.

Underbuilt fiber optic cable:

- Use of an underbuilt fiber optic cable in conjunction with an overhead fiber optic cable, or use of two underbuilt fiber optic cables, is acceptable for dual pilot protection. However, as in Two permissive tripping schemes with Two Independent fiber optic shield wires, outside interference such as an aircraft could cause the loss of both fiber paths during a fault.

Independent fiber paths are not required for the following:

- If at least one of the pilot schemes is a blocking scheme
- Loss of the channel will not disable the high speed tripping of the blocking scheme. However, system security implications with the application of a blocking scheme must be considered.
- If at least one of the pilot schemes is a current differential scheme, which reverts to a sensitive overcurrent element or otherwise provides for high speed tripping for the entire line on loss of channel.

Fiber Optic Multiplexed Communications

- If the fiber optic channel utilizes multiplexing equipment, the failure of this equipment must be considered when evaluating susceptibility to a single mode failure. A single mode failure must not result in the unavailability of both pilot protection systems for longer than the switching time from normal to alternate facilities which normally occur within milliseconds of a channel failure.

Fiber Optic Self-healing Ring Topology

- Fiber optic systems utilizing a self-healing ring topology can be utilized to provide path redundancy. However, the failure of the multiplexing/switching equipment must not result in the unavailability of both pilot protection systems

Note:

In a DCUB (Directional Comparison Unblocking) scheme, tripping is typically permitted for 100-300 msec following the loss of the received signal.

Appendix D: Small Generator Protection Requirements

For generating units less than 100 MVA and connected below 200 kV and not previously addressed in this document, generation developers are referred to the following sources of requirements depending on generator size.

- Generators < 20 MVA: Refer to PJM Manual 14GA, Attachments CE and DE-1
- Generators \geq 20 MVA and <100 MVA: Refer to requirements of the applicable transmission owner.

The following standards and publications can also be used as a reference for developing the requirements for applicable small generator protections:

- IEEE 1547-2018 - IEEE Standard for Interconnection and Interoperability of Distributed Energy Resources with Associated Electric Power Systems Interfaces

Appendix E: Acceptable Three Terminal Line Applications

This appendix outlines the categories of three terminal line applications and associated protection requirements which have been deemed acceptable for use within PJM. Three terminal line applications are only permitted at voltages less than 300 kV when the requirements listed below are met. No three terminal line applications are permitted on systems at 300 kV and above.

1.0 Category I – Temporary Installation

This category applies when an acceptable long-term reinforcement was already identified but cannot be installed in time and consequently the reliability of the transmission system may be compromised. Examples include construction delays, unusual combinations of system demand and long term transmission equipment forced outages. The three terminal line configurations must be removed when the planned permanent reinforcement is in place.

The following requirements apply to Category I installations.

1.1 Protection Requirements

A detailed relay coordination review must be performed which establishes that the planned addition will result in no compromises to coordination. The review shall include consideration of apparent impedances at each terminal, weak sources, fault current nulls or outflows.

The protection scheme(s) must be designed to provide high-speed (pilot) clearing of faults at all locations on the three terminal line. Designing for sequential clearing of faults is not acceptable.

Backup protection must be provided and applied such that for faults anywhere on the circuit, each terminal shall be able to detect the fault and initiate tripping without regard to whether the other terminals have opened or are still closed.

The backup line protection may be pilot (high-speed, communications dependent) or non-pilot (stepped-distance, ground time overcurrent) depending on the specific circumstances and results of fault and stability studies, etc. Each affected Transmission Owner will evaluate the proposed installations on a case-by-case basis. If a backup high-speed pilot scheme is required, the requirements for dual pilot channels outlined in Appendix C of this document must be met.

2.0 Category II – Permanent Installation

2.1 Protection Requirements

A detailed relay coordination review must be performed which establishes that the planned addition will result in no compromises to coordination. The review shall include consideration of apparent impedances at each terminal, weak sources, fault current nulls or outflows.

The protection scheme(s) must be designed to provide high-speed (pilot) clearing of faults at all locations on the three terminal line. Designing for sequential clearing of faults is not acceptable.

Backup relays must be provided and applied such that for faults anywhere on the circuit, each terminal shall be able to detect the fault and initiate tripping without regard to whether the other terminals have opened or are still closed.

The backup line protection may be pilot (high-speed, communications dependent) or non-pilot (stepped-distance, ground time overcurrent) depending on the specific circumstances and results of fault and stability studies, etc. Each affected Transmission Owner will evaluate the

proposed installations on a case-by-case basis. If a backup high-speed pilot scheme is required, the requirements for dual pilot channels outlined in Appendix C of this document must be met.

For reliability reasons, extending an existing two-terminal directional comparison blocking or unblocking scheme operating over power line carrier to a third terminal is not acceptable for primary or backup line protection.

In all cases where a pilot scheme is required, digital communications channels between the three terminals must be used. No portions of these channels may be metallic (i.e. telephone cable, coaxial cable, etc.) other than between relays and multiplex equipment (where used) within the control house. External audio-tone interfaces are not acceptable. Where multiplexing schemes are used, they must be evaluated with respect to the characteristics of the proposed protection (i.e. susceptibility to mal-operation due to variances in path delay) on a case-by-case basis.

Revision History

Revision 03 (05/24/2018):

- Revised Manual Owner from Mark Sims to Aaron Berner
- Added new section on Reliability related requirements. It details new consensus requirements on Test Switches, Instrument Transformers, Communication Channels, Station Batteries and Station Service (AC).
- Updated references to current versions of NERC Standards
- Added the new NERC name for Special Protection Schemes (SPS) which is Remedial Action Schemes (RAS)

Revision 02 (07/01/2016):

- Manual Ownership changed from Paul McGlynn to Mark Sims
- Section 7: Line Protection reworded to clarify the terms “Primary” and “Backup” and specified PJM Planning Department to review and approve out-of-step relay and single-phase tripping applications.
- Section 8: Substation Transformer Protection revised to better account for practices of all member TOs.
- Power Line Carrier requirements added to Appendix B: Direct Transfer Trip.
- Power Line Carrier added and Fiber Optic Systems rearranged in Appendix C: Dual Pilot Channels.
- Removed Appendix F: Triggered Current Limiters.
- Cover to Cover Periodic Review

Revision 01 (02/27/2014):

- Revised Sections 7-Line Protection and 8-Substation Transformer Protection to align better with the PJM Relay Subcommittee Protective Relaying Philosophy and Design Guidelines.

Revision 00 (11/16/2011):

- This is a new manual. This manual establishes the minimum design standards and requirements for the protection systems associated with the bulk power facilities within PJM.